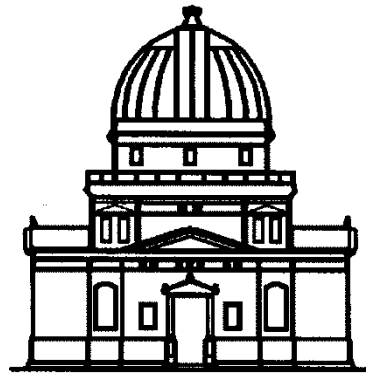


# Introduction to Radioastronomy:

## The radio telescopes at ISU

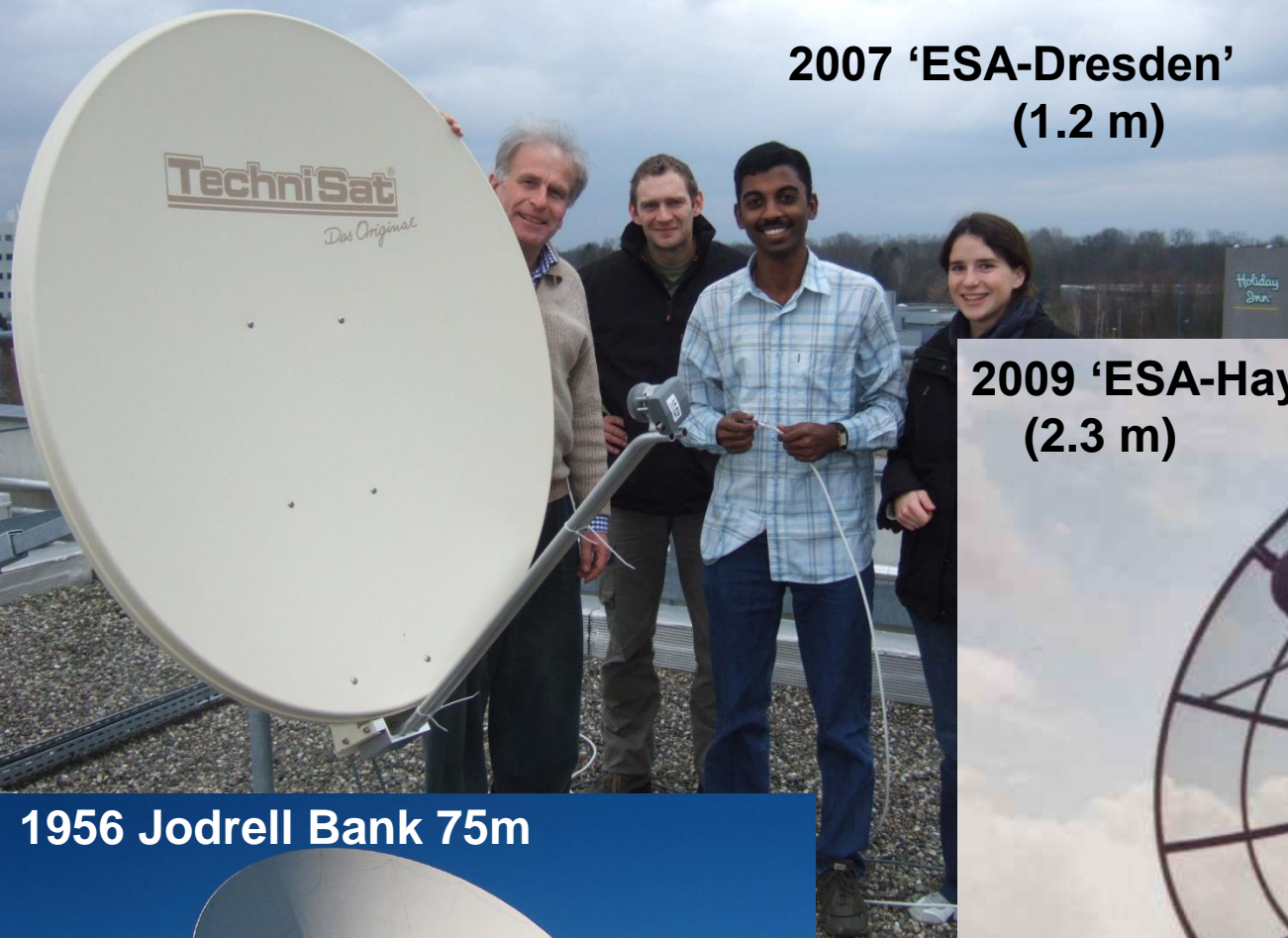


Observatoire astronomique  
de Strasbourg

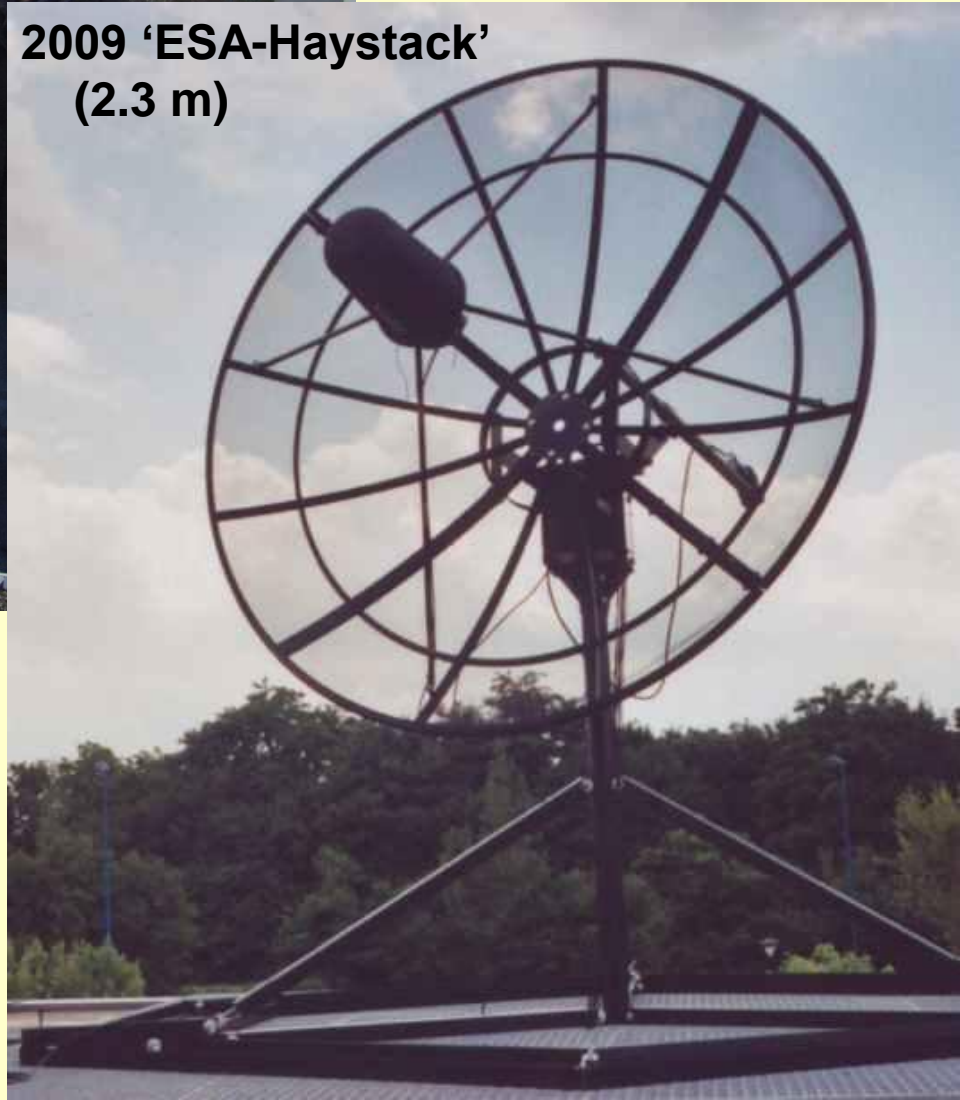
J.Köppen      joachim.koppen@astro.unistra.fr

<http://astro.u-strasbg.fr/~koppen/JKHome.html>

2007 'ESA-Dresden'  
(1.2 m)



2009 'ESA-Haystack'  
(2.3 m)



1956 Jodrell Bank 75m



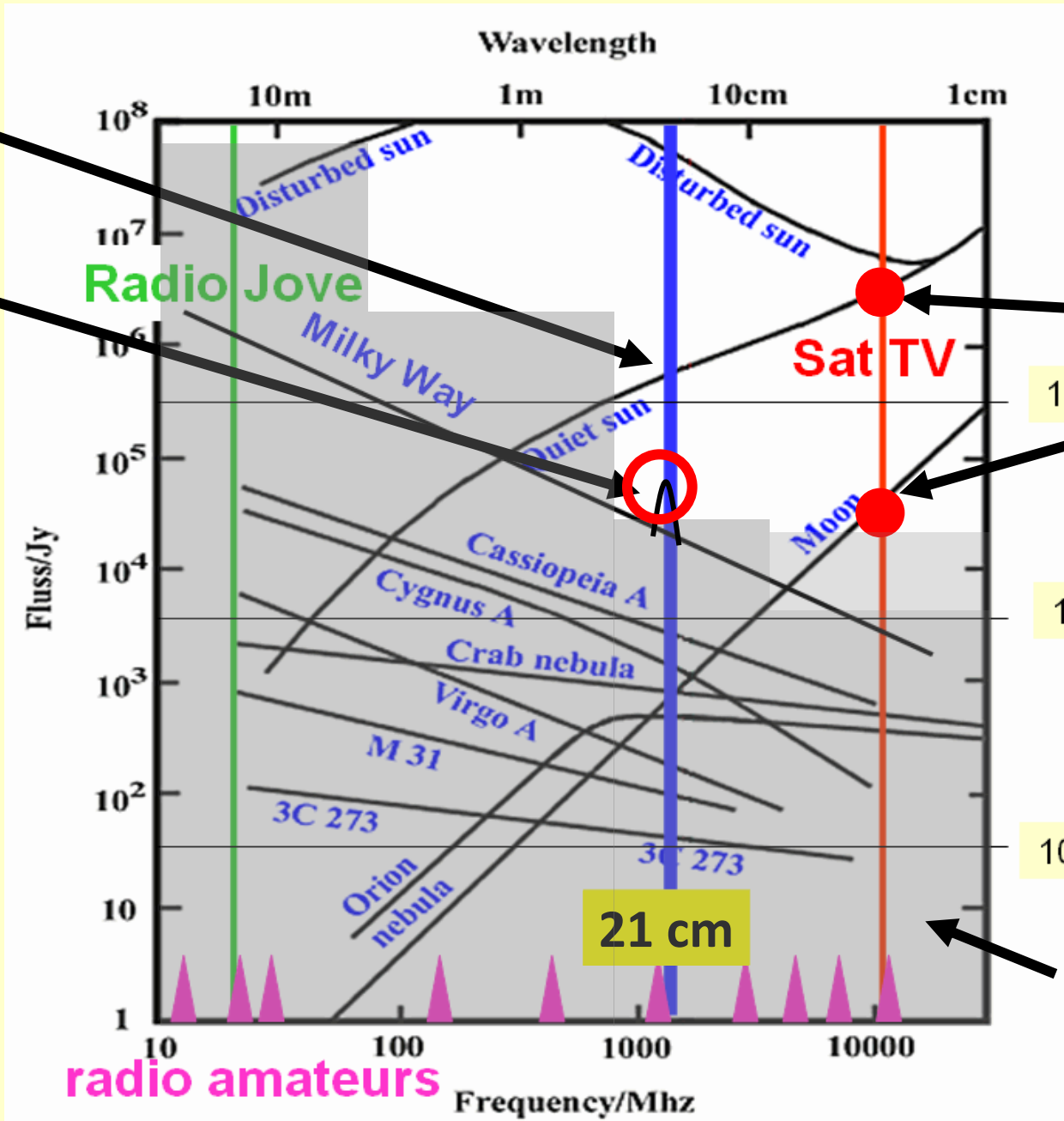
# What we can observe



Haystack



GENSO



Dresden

radio amateurs

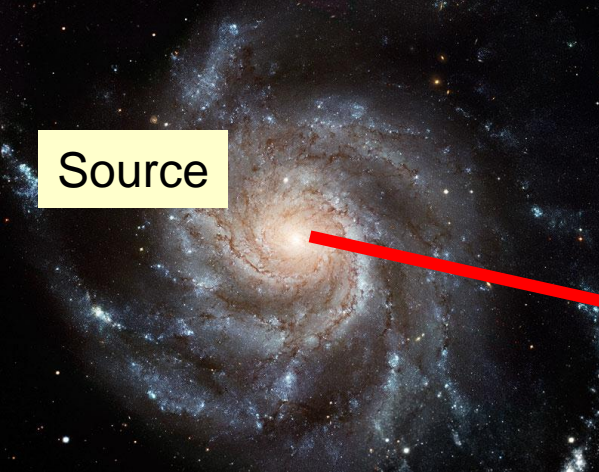
# ISU's two Radiotelescopes

	<b>ESA-Dresden</b>	<b>ESA-Haystack</b>
Frequency	<b>10 ... 12 GHz (continuum)</b>	<b>1.420 GHz (HI line)</b>
Wavelength	<b>3 cm</b>	<b>21 cm</b>
Dish diameter	<b>1.2 m</b>	<b>2.3 m</b>
HPBW (ang.resolution)	<b>1.5°</b>	<b>6°</b>
Time for full solar scan	<b>30 min</b>	<b>2 hrs (!)</b>
Suitable objects	<b>Sun, Moon, (TV satellites)</b>	<b>Sun, Milky Way</b>
We measure	<b>absolute fluxes (give temperatures, Radiometer)</b>	<b>spectra, radial velocities of H gas clouds (Spectrometer)</b>
Positional accuracy and stability	<b>±1° (at best!)</b>	<b>±0.5°</b>
operation	<b>manual</b>	<b>Manual &amp; Batch</b>

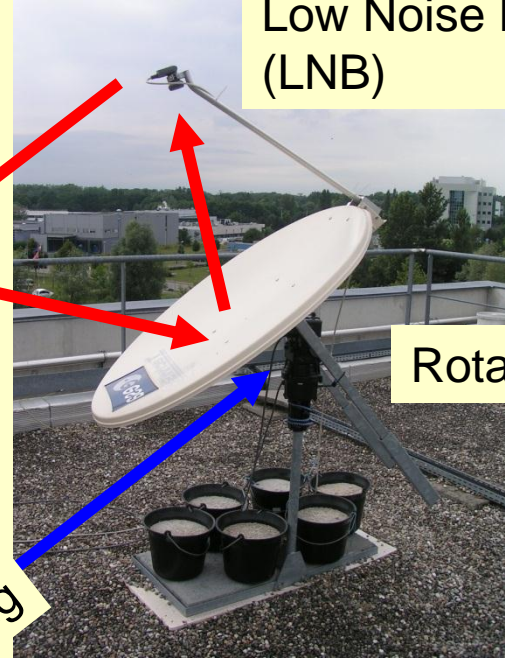
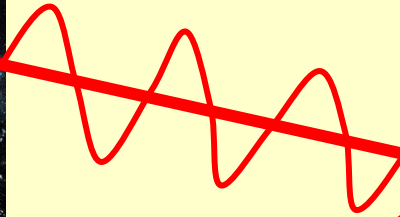
# The ESA-Dresden Telescope

- Frequency 10..12 GHz (wavelength 3 cm)
- Radiometer
- 1.2 m diameter satellite TV antenna
- Sun, Moon, (TV satellites)
- <http://astro.u-strasbg.fr/~koppen/10GHz/>





Source



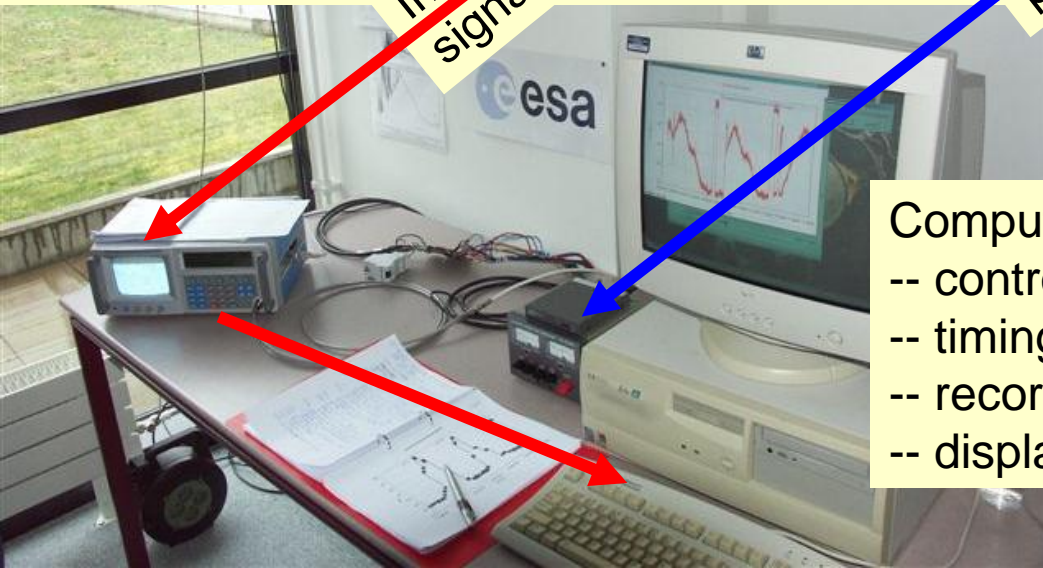
Antenna with Low Noise Block (LNB)

Rotators

Receiver

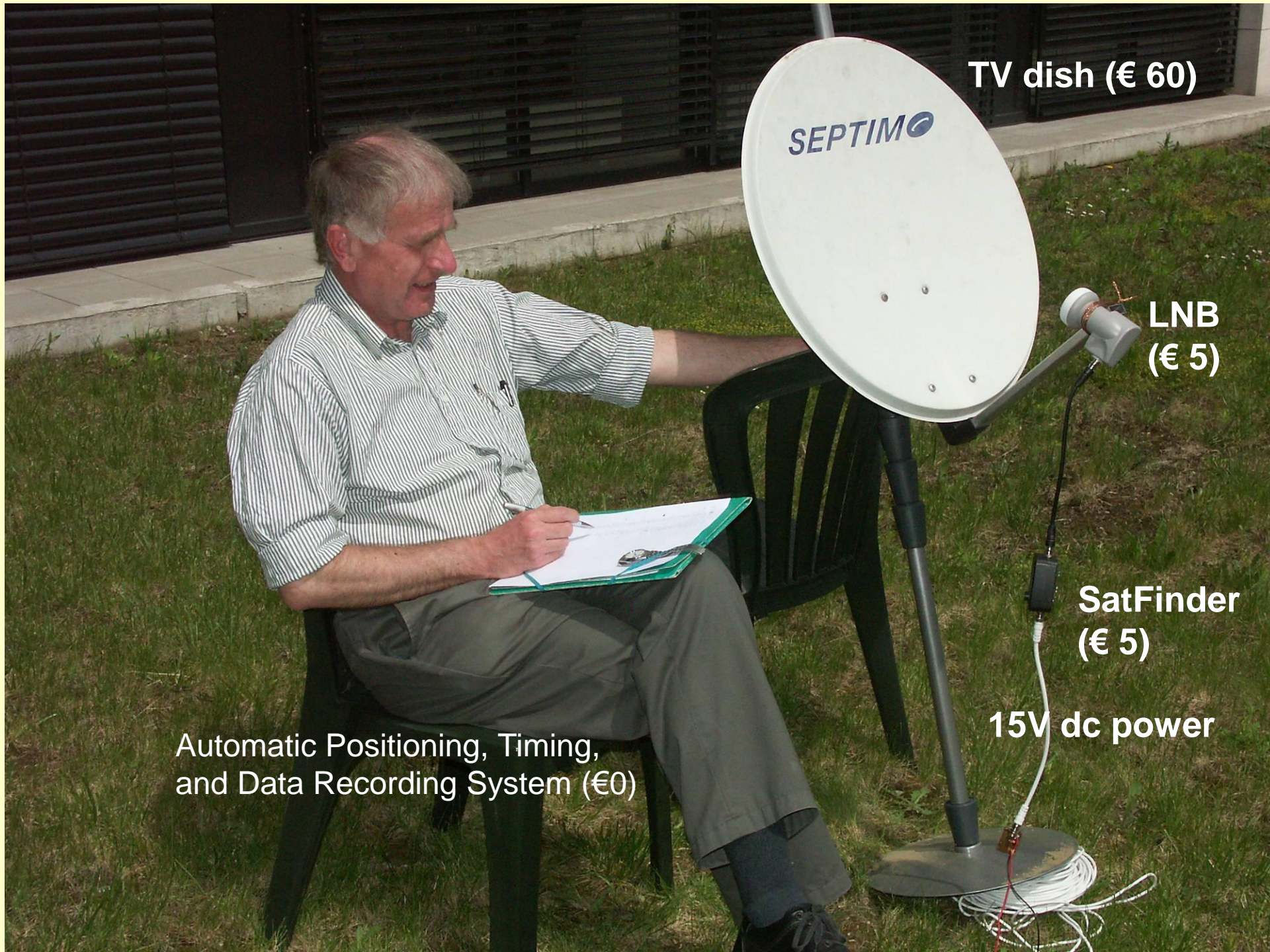
Intermediate frequency signal

Antenna positioning



Computer:  
-- controls  
-- timing  
-- record data  
-- display





**TV dish (€ 60)**

**LNB  
(€ 5)**

**SatFinder  
(€ 5)**

**15V dc power**

**Automatic Positioning, Timing,  
and Data Recording System (€0)**



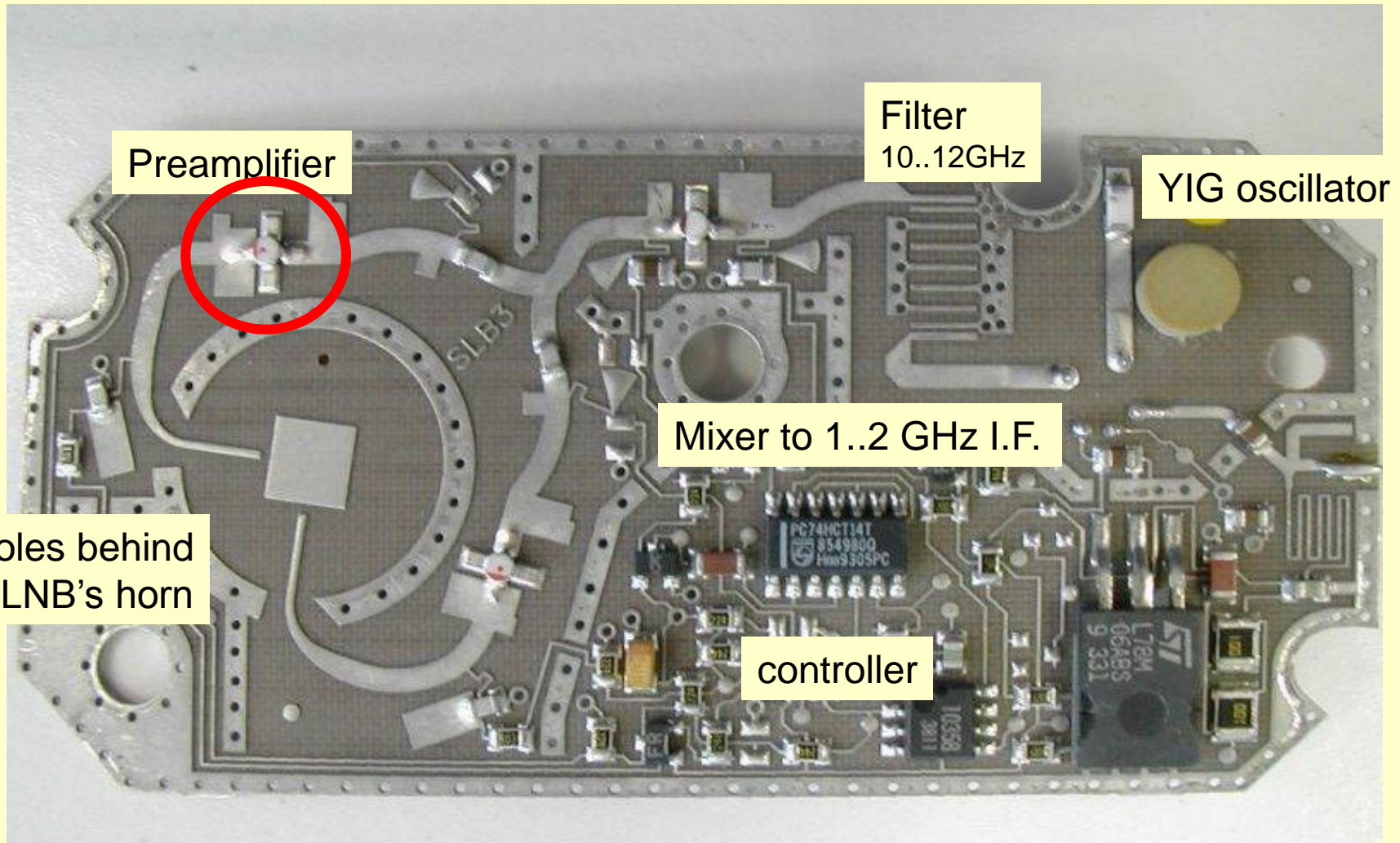
# On the roof

- 1.2m offset parabolic reflector
- Rotators for azimuth and elevation
- Low noise block (LNB):
  - Small horn antenna catches radio wave
  - Dipole senses radio wave, converts it into electrical signal
  - Preamplifier boosts signal (makes the background noise)
  - This 11 GHz signal is converted (mixed) to lower intermediate frequency (I.F., 1..2 GHz)
- Coaxial cable to observatory room





# Inside a SatTV LNB



# In the Observatory room

- Receiver measures strength of I.F. signal
  - in  $\mu\text{V}$  at its input terminal
  - one measurement every 2 sec
  - data are passed to computer for storage and display
- Rotator controller with computer interface
- Computer software provides graphical interface to user:
  - Controls: position, frequency, start/stop measuring ...
  - Display: current position, measured data, ...
  - predict Sun and Moon position

Operate

Skyview

Spectrum

Scan

Map

Pos.Calib.

Settings

Exit

station

ISU\_Illkirch at -7.75°W 48.65°N

UT 12:40:23

Shutdown System

Simulation

goto Calibrator

goto Astra 1

Sun now

Sun+15m

Moon now

Moon+15m

current Position

true AZ/EL =

203.1

43.9

our AZ/EL =

236

44

true AZ/EL =

203.6

43.8

Goto

our AZ/EL =

236

44

freq. [MHz]

12500

Horiz.Polar.

averag.over:

1

single measmt.

Observe & Record:

Start

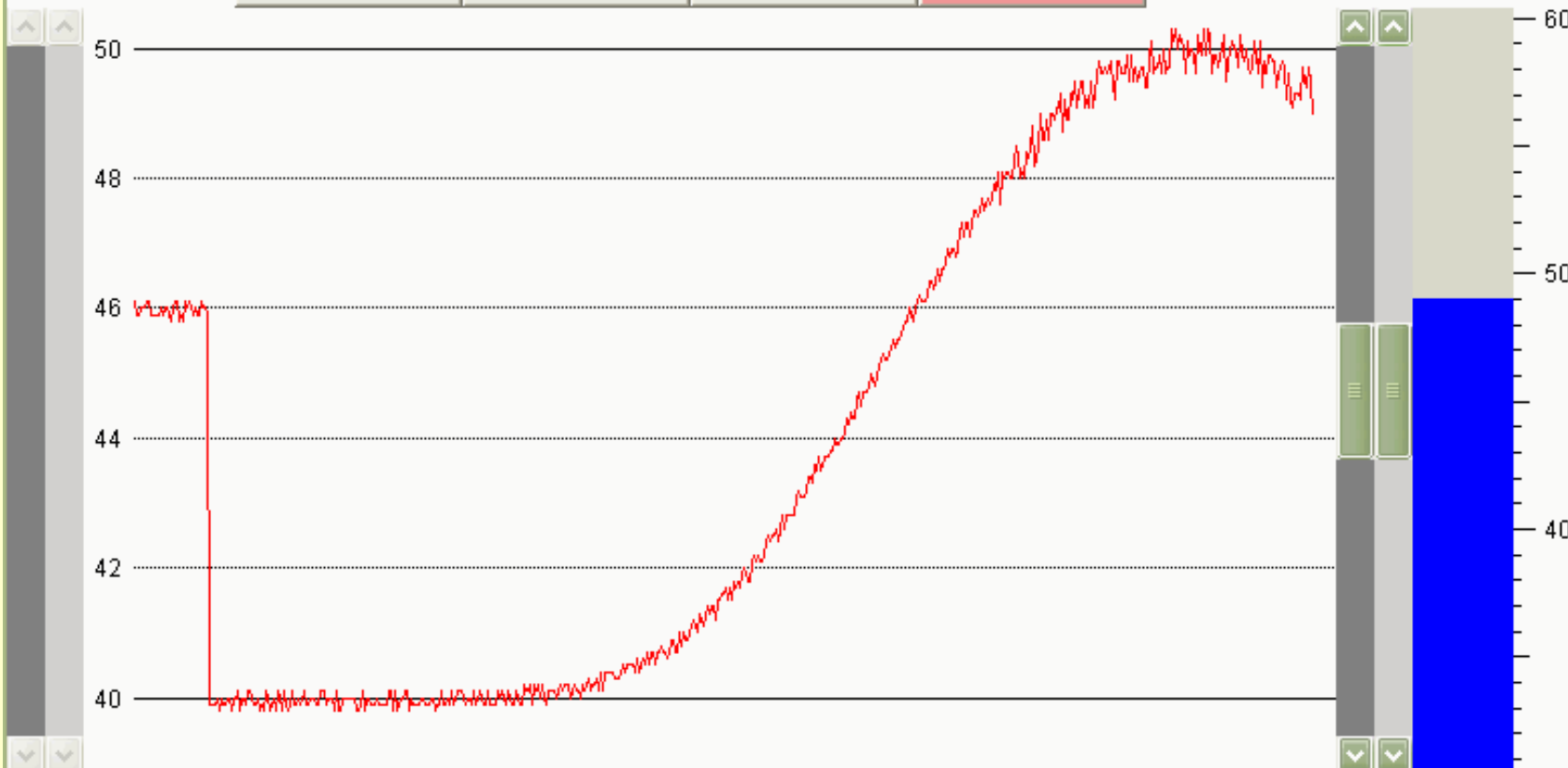
Stop

Resume

Stop+Finish

power [dBμV] =

49.0

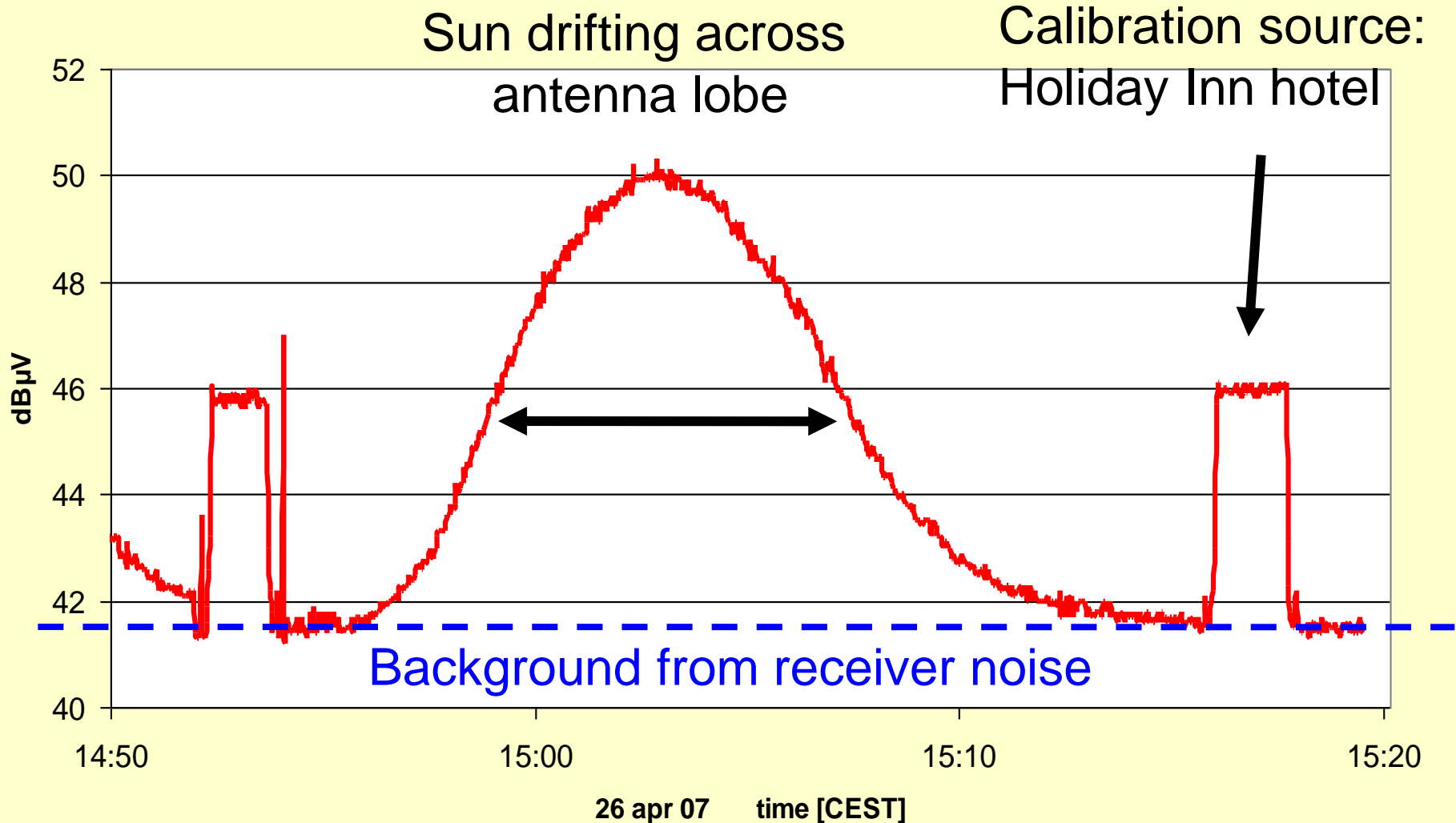




# How to measure the surface temperatures of Sun and Moon

- Observe the passage of the sun through the antenna beam (we utilize the Earth's rotation!):
  - Maximum gives radio flux from the sun
  - The profile gives the width of antenna beam, needed to determine the beam filling factor
- Flux from calibrator source = source of known temperature = the ground (290 K)
- Observe empty sky = determine background noise (mainly from the front end (LNB) of the receiver system)

# An example: the raw data



# Preview of analysis

- reduce and calibrate the measured power

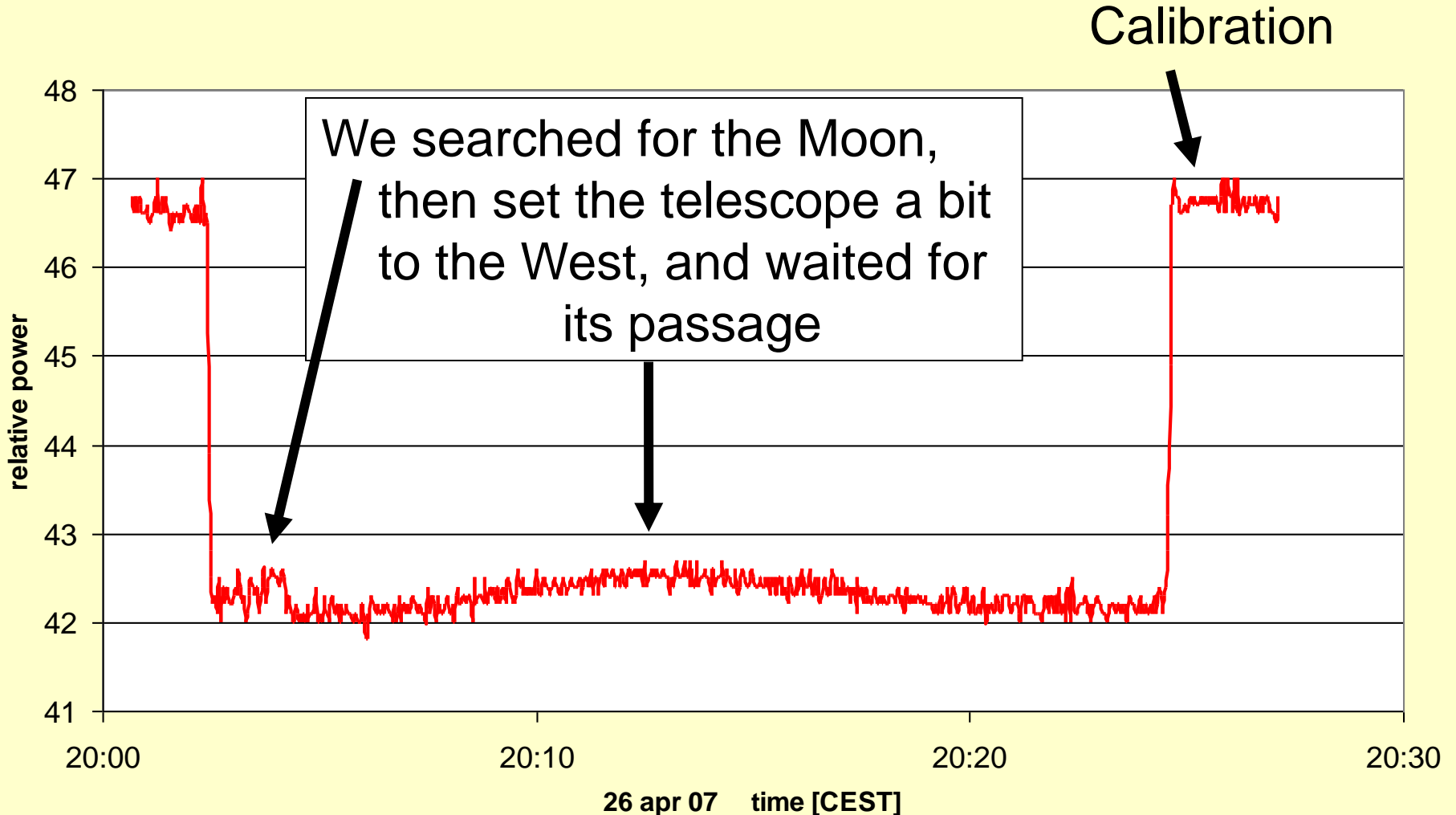
$$T_{\text{Ant}} = (P_{\text{Sun}} - P_{\text{Sky}}) / (P_{\text{Cal}} - P_{\text{Sky}}) * 290 \text{ K}$$

- the Sun does not fill the antenna beam:  
angular diameter  $D_{\text{Sun}} = 0.5^\circ < \text{HPBW!}$

$$T_{\text{Surf}} = T_{\text{Ant}} * (\text{HPBW} / D_{\text{Sun}})^2$$



# The same thing for the Moon is somewhat more delicate



UT 12:41:22

time + 1 h

time - 1 h

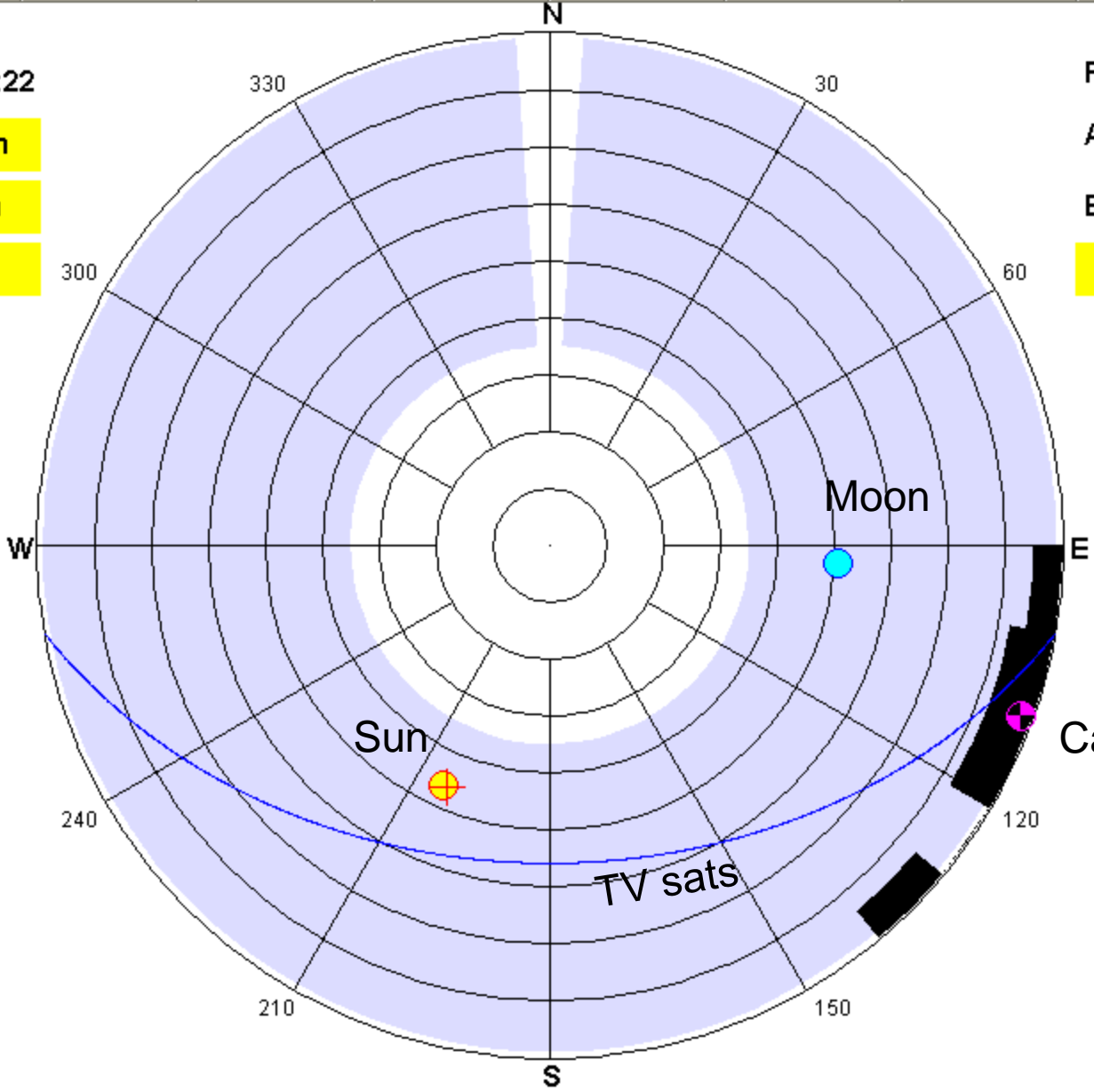
now

Position

AZ = 203

EL = 44

Goto



# Drift scans of the Sun

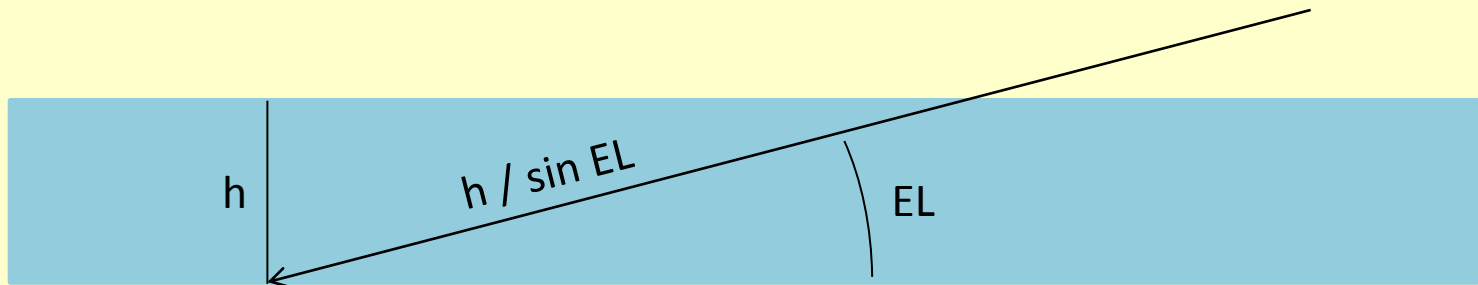
- A half-scan is easy at any time:
  - **goto Calibrator**, measure for 2 min
  - **Sun now** , **Goto**
  - find best position manually
  - (perhaps move a tiny bit to the West (right))
  - let the Sun drift across the beam
  - When signal becomes low and constant, you have the sky, then **goto Calibrator** (2 min)
- A full scan is best done near lunch-time



# However: the background ...

... is the sum of

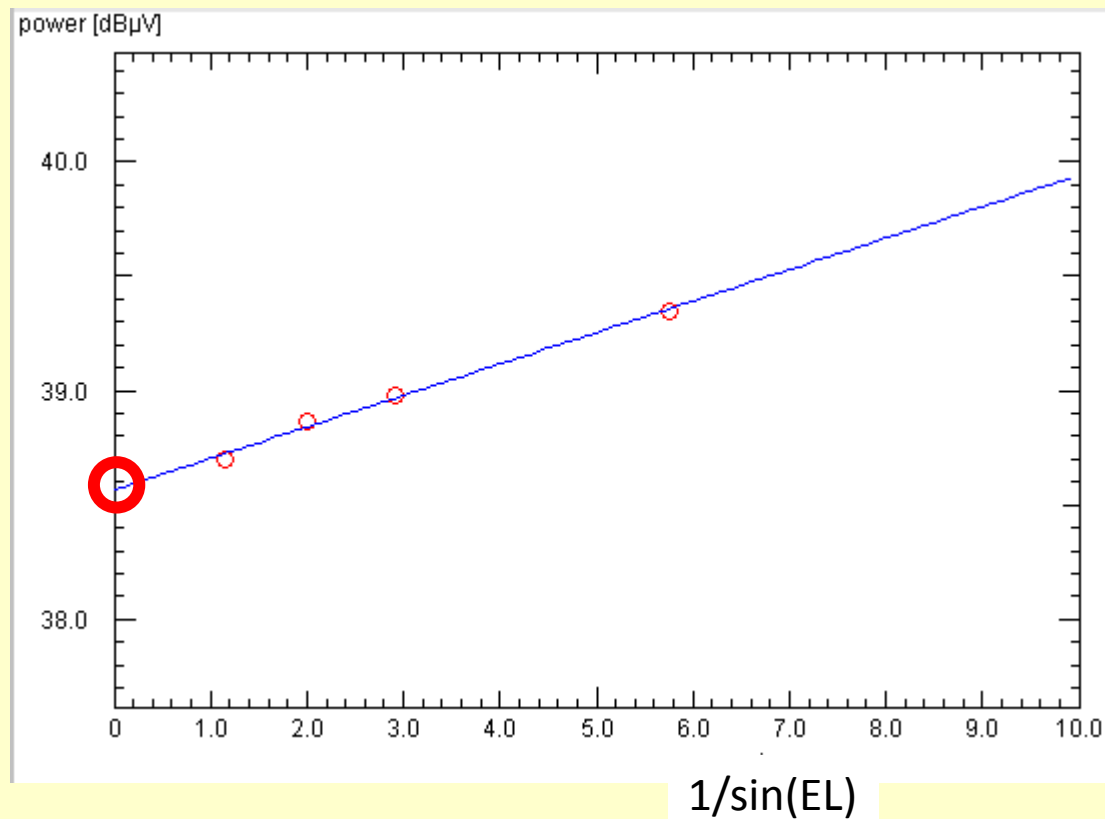
- the receiver noise, which is constant at all positions
- and the sky noise, which increases with lower elevation angle as we look through a longer path through the atmosphere:



- $P_{\text{backgrd}}(\text{EL}) = P_{\text{RX}} + P_{\text{sky}} / \sin(\text{EL})$

# How to do it

- Measure sky noise at several elevations (needs extra time 😞 10 min at 10°, 20°, 30°, 60°)
- Fit the data with the above relation, to get  $P_{RX}$



... and apply it

$$T_{\text{Ant}} = (P_{\text{Sun}} - P_{\text{Backgrd}}(EL)) / (P_{\text{Cal}} - P_{\text{RX}}) * 290 \text{ K}$$

when we observe the sun, the background noise is from receiver **and** the sky at that elevation EL

but when we look at the calibrator, the background is only receiver noise!

# Simulation with the Trainer applet

<http://astro.u-strasbg.fr/~koppen/10GHz/applets/trainer/>

- In contrast to the real telescope, the simulator's positioning is perfect: use **sun+15min** to lay in wait for the sun
- Data are obtained by grabbing the text from the **Output** screen

# Reality: Bag of Tricks I

- The positioning system was never designed to point at such small sources ... but we can do it!
- → find the best position manually → we must be present during observations
- **Stop** measuring, receiver outputs signal more often! ... then **Resume**
- it's best done with the controller keys





# Bag of Tricks II

- Run 'RadioAstro' to establish port communication:
  - Open ...
  - The current position numbers should appear
  - Close ...
  - Exit the program
- Run 'ESA-Dresden' software
  - Start



# Bag of Tricks III

- In principle, the electronics needs about 2 hours to warm up to equilibrium temperature
- During that time, there will be drifts in the displayed position ( $5^\circ$  in Az) and the measured power levels (0.3 dB) ... don't worry!
- If you keep that in mind, you can observe without waiting 😊!